

Discussion of The Small  $n$  Problem  
By Glen Cowan  
and  
Bayesian Methods in Particle Physics  
From Small  $N$  to Large  
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## Themes

### Both Papers

- Confidence Limits
- Discovery

### Prosper: The Classification Problem

- Marks: Variables observed with events
- Different distributions for background and signal

**Brief Outline:** Confidence; Discovery; (try to) connect Discovery to Classification.

## Confidence Limits for $s$ The Small $n$ Problem

**The Simplest Case:** Given

$$N = N_b + N_s \sim \text{Poisson}(b + s)$$

where  $b$  is known and  $s$  is unknown, find an upper limit for  $s$ .

**Litmus Tests:**

- Equivariance under transformations,  $s' = \phi(s)$ .
- No dependence on  $b$  when  $N = 0$ .

**Note:** If  $N = 0$ , then  $N_b = 0$  and  $N_s = 0$ .

## Confidence: Continued

### Classical Solutions

- Invert UMP Tests of  $H_0 : s \geq s_0$ .
- Regions of high relative likelihood, the one-sided case.

**Litmus Tests:** Equivariant, but can depend on  $b$  when  $N = 0$ .

**Example: KARMEN:** When  $b = 3$  and  $N = 0$ , the UMP limit is negative and the RHL is 1.08, for a 90% interval.

## The Uniform Bayesian Solution

**Posterior Distributions:** If  $s \sim \text{Uniform}(0, \infty)$ , then

$$P[s > s_0 | n] = \frac{\int_{s_0}^{\infty} (b + s)^n e^{-(b+s)} ds / n!}{\int_0^{\infty} (b + s)^n e^{-(b+s)} ds / n!} = \frac{\int_{b+s_0}^{\infty} t^n e^{-t} dt}{\int_b^{\infty} t^n e^{-t} dt}$$

**Credible Sets:** A level  $1 - \gamma$  credible set is  $s \leq s_{\text{up}}(n)$ , where

$$P[s > s_{\text{up}}(n) | n] = \gamma.$$

**Example: KARMEN:** When  $b = 3$  and  $N = 0$ ,  $s_{\text{up}} = 2.31$ .

**Litmus Tests:** Independent of  $b$  when  $n = 0$ , but the uniform prior is not invariant.

## The Uniform Bayesian Solution: Continued AKA: The Conditional Frequentist Solution

Find:

$$P[s > s_0 | n] = P_{s_0}[N \leq n | N_b \leq n].$$

Solve

$$P_{s_{\text{up}}(n)}[N \leq n | N_b \leq n] = \gamma. \quad (*)$$

Then

$$P_s[s \leq s_{\text{up}}(N)] = \dots \geq 1 - \gamma.$$

**Notes 1:** The construction in (\*) is equivariant under parameter transformations.

**2.** Forget the Bayesian derivation; keep the answer. [Roe and W. (1999, *Phys. Rev.*, D)]

## Complications

**Intervals:** Both Bayes and RHL extend

**Nuisance Paramters:** Unknown  $b$ , but  $M \sim \text{Poisson}(\tau b)$ .

- Prosper: conjugate priors.
- Heinrich: confidence limits with non-informative priors.

## Frequentist

- RHL: Approximate,  $P_{s, \hat{b}_s} [s \leq s_{\text{up}}] \geq 1 - \gamma$ .
- Hybrid resampling [Chuang and Lai (2000, *Statistica Sinica*)].

**Marks:** Can be included, except for conditional frequentist [Roe and W. (2000), *Phys. Rev, D.*].

## Foundations

### Bayesian Methods in Particle Physics

#### Points of Agreements

- (Subjective) Bayes is coherent
- Bayes is interesting, and useful.
- Both Bayesian and Frequentist approaches are needed.

#### Other Points

- May not have a prior, especially in high dimensional problem
- Mixtures of conjugate priors.

## A Toy Example

**Model:**  $X \sim \text{Normal}(\mu, \sigma^2)$

**Goal:** Estimate  $\theta = \mu^2$

### Estimators

**MLE**  $\hat{\theta} = X^2$ .

**Unbiased**  $\hat{\theta} = X^2 - \sigma^2$

**Uniform Bayes**  $\hat{\theta} = X^2 + \sigma^2$

### Properties

- Unbiased can be negative.
- Bayes is inadmissible.

## The Discovery Problem

**Marks:** Suppose:

- $N = N_b + N_s$ , as above
- With each event a mark  $X$  is observed; and

$$f(x) = \frac{bf_b(x) + sf_s(x)}{b + s}.$$

**Classification:** For a single event,

$$P[\text{Signal}|X = x] = \frac{sf_s(x)}{bf_b(x) + sf_s(x)}.$$

### Unknown Parameters

- Bayesian: Conjugate priors or Simulation.
- Frequentist: Maximum Likelihood, using EM.

## An Application to Astronomy

### Observations from Sextans

- Members or foreground stars.
- $X$  = position and velocity.
- Velocity is normal given position.
- Interest in velocity dispersions.

### Analysis

- (Almost) a full likelihood analysis, using EM.
- Uses estimated probability of membership in a weighted log-likelihood.

**Ref:** Sen and Walker, Poster.

## The Discovery Problem

**Recall:**  $N \sim \text{Poisson}(b + s)$  and  $X_1, \dots, X_n \sim^{\text{ind}} f|n$ .

### Likelihood

$$L(s|\text{Data}) = \frac{1}{n!} e^{-(b+s)} \prod_{i=1}^n [b f_b(x_i) + s f_s(x_i)].$$

**Prior Distribution:** Let

$$\Pi(t) = P[s \leq t]$$

$$\pi_0 = P[s = 0],$$

and

$$\pi(t)dt = P[t \leq s \leq t + dt | s > 0].$$

## Conventional Formulation

Test  $H_0 : s = 0$

**Posterior Probability:** If  $N = n$ ,  $X_1 = x_1, \dots$ , and  $X = x_n$ , then

$$\pi_0^* = P[S = 0|\text{Data}] = \frac{\pi_0}{\pi_0 + (1 - \pi_0)B},$$

where

$$B = \int_0^\infty \frac{L(s|\text{Data})}{L(0|\text{Data})} \pi(s) ds$$

**Note:** Depends crucially on  $\pi_0$ .

If  $\pi_0 = 0$ , then  $\pi_0^* = 0$  for any  $n$  and  $x_1, \dots, x_n$ .

## In More Detail

$$B = \sum_{k=0}^n \frac{1}{b^k} C_{n,k} \int_0^{\infty} s^k e^{-s} \pi(s) ds,$$

where

$$C_{n,k} = \sum_{j_1 + \dots + j_n = k} \prod_{i=1}^n \left( \frac{f_s(x_i)}{f_b(x_i)} \right)^{j_i}.$$

and  $j_i = 0$  or  $1$ .

**The Uniform Case.** If  $\pi(s) \equiv 1$ , then

$$B = \sum_{k=0}^n \frac{k!}{b^k} C_{n,k}.$$

## Alternative Formulation

Have we Seen a Signal Yet: Is  $N_s > 0$ ?

Find:

$$P[N_s = 0 | \text{Data}] = \frac{\int_0^\infty e^{-s} d\Pi(s)}{\sum_{k=0}^n \binom{n}{k} b^{-k} C_{n,k} \int_0^\infty s^k e^{-s} d\Pi(s)}.$$

**Dependence on  $\pi_0$** ; Apparently, less.

**Notes 1:** Can have  $\pi_0 = 0$  and  $P[N_s = 0 | \text{Data}] \approx 1$ .

**2.** Simplifies in the Uniform Case.

**3.** Implicit in the Classification Problem.

**4.** Another alternative: consider posterior expected distance of  $s$  from 0.